#### SMT Solvers

#### **Cristian Cadar**



Department of Computing Imperial College London

Imperial College London

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- SAT solvers operate at the level of Boolean or propositional formulas
- Many application domains generate constraints at a higher level
- SMT supports rich *theories* in classical *first-order logic with equality*

## SMT Theories

- A theory consists of a signature  $S_T$  and axioms  $A_T$
- S<sub>T</sub> consists of 3 types of constants:
  - Object constants refer to objects in the universe of discourse, e.g, *John, Mary*,... for universe of people
  - Function constants refer to functions
    - Each function has an associated arity, e.g., *parent* has arity 1
    - Object constants can be seen as function constants with arity 0
  - Predicate constants refer to relations between objects
    - Each predicate has an associated arity, e.g., *likes* has arity 2
- A<sub>T</sub> consists of **axioms** which interpret some functions and predicates

## Theory of Equality $T_{=}$

• Also referred to as empty theory

$$- S_{T_{=}}: \{=, a, b, c, \dots, f, g, h, \dots, p, q, r, \dots\}$$

- f, g, ..., p, q, ... are *uninterpreted* functions and predicates
- "Built-in" predicate = is *interpreted* by axioms  $A_{T_{=}}$ :

$$- \forall x. x = x$$
 (reflexivity)  

$$- \forall x, y. x = y = y = x$$
 (symmetry)  

$$- \forall x, y, z. x = y \land y = z => x = z$$
 (transitivity)  

$$- \forall x_1, \dots, x_n, y_1, \dots y_n. \land x_i = y_i => f(x_1, \dots x_n) = f(y_1, \dots y_n)$$
 (function congruence)

$$- \forall x_1, \dots, x_n, y_1, \dots, y_n. \land x_i = y_i \Rightarrow p(x_1, \dots, x_n) \Leftrightarrow p(y_1, \dots, y_n)$$
  
(predicate congruence)

## Theory of Equality $T_{=}$

- Also known as theory of equality with uninterpreted functions
- Uninterpreted functions are useful as an abstraction or over-approximation mechanism
  - Remember static program verification

## Theory of Presburger Arithmetic

• Presburger arithmetic: allows only addition over natural numbers

• 
$$S_{\mathbb{N}}$$
: {0, 1, =, +}

•  $A_{\mathbb{N}}$ :  $- \forall x. \neg(x+1=0)$  (zero)  $- \forall x. x+0=0$  (plus zero)  $- \forall x. y. x+1=y+1=>x=y$  (successor)  $- \forall x, y. x+(y+1)=(x+y)+1$  (plus successor)  $- F[0] \land (\forall x. F[x]=>F[x+1])=> \forall x.F[x]$  (induction)

## Theory of Fixed-width Bitvectors

- Object constants are fixed-width bitvectors, e.g., 011011, 001
- Functions include extraction, concatenation, bitwise operations, arithmetic operations

## Theory of Arrays

- $S_A$ : {a, b, c, ..., i, j, k, ...v, w, ..., =, read, write)
- At a high-level:
  - read(a, i) is a binary function that returns the value of array a at index i
  - write(a, i, v) is a ternary function that returns an array identical to a except that at index i it has value v

- $\forall a, i, j. i = j => read(a, i) = read(a, j)$  (array congruence)
- $\forall a, i, j, v. i = j \Rightarrow read(write(a, i, v), j) = v \qquad (read-over-write 1)$
- $\forall$  a, i, j, v.  $\neg$ (i = j) => read(write(a, i, v), j) = read(a, j) (read-over-write 2)

# Solving SMT queries

- Eager translation to equisatisfiable SAT formula
  - Some theories are better matches than others
  - Multiple translations possible, SMT solver performs several transformations/optimizations in the process using information available at the theory level
    - E.g., simplifying x –x to 0.

#### • DPLL[T]

Adapts DPLL to work at the level of theory T (theory deduction, theory conflicts, etc.)

#### **Combination of Theories**

- Given
  - theory  $T_1$  with signature  $S_{T_1}$  and axioms  $A_{T_1}$
  - theory  $T_2$  with signature  $S_{T_2}$  and axioms  $A_{T_2}$
  - an SMT solver for T<sub>1</sub>
  - an SMT solver for T<sub>2</sub>
- Can we produce a solver for  $T_1 \cup T_2$ ?
  - $-\operatorname{T}_1 \cup \operatorname{T}_2$  with signature  $\operatorname{S}_{\operatorname{T}_1} \cup \operatorname{S}_{\operatorname{T}_2}$  and axioms  $\operatorname{A}_{\operatorname{T}_1} \cup \operatorname{A}_{\operatorname{T}_2}$

## Nelson-Oppen Framework

- Framework for deciding combined theories under certain assumptions, e.g, only for quantifier-free theories
- Examples
  - theory of arrays and bitvectors
  - theory of arrays and integers

## Nelson-Oppen Framework

- Two phases:
  - **Purification**: transform F into equisatisfiable formula  $F' = F_1 \wedge F_2$  such that
    - F<sub>1</sub> belongs only to T<sub>1</sub>
    - F<sub>2</sub> belongs only to T<sub>2</sub>
  - Equality propagation: propagate equalities between theories

#### STP solver

- SMT solver for the theory of bitvectors and arrays
- Based on *eager* translation to SAT (uses MiniSAT)
- Developed at Stanford by Ganesh and Dill, initially targeted to, and driven by, EXE

## Theory of Bitvectors and Arrays

- Can accurately encode the semantics of C programs
  - Model each memory block as an array of 8-bit BVs
  - Bind types to expressions, not bits

#### char buf[N]; // symbolic

struct pkt1 { char x, y, v, w; int z; } \*pa = (struct pkt1\*) buf;

struct pkt2 { unsigned i, j; } \*pb = (struct pkt2\*) buf;

if (pa[2].v < 0) { assert(pb[2].i >= 1<<23); }

buf: ARRAY BITVECTOR(32)OF BITVECTOR(8)

SBVLT (buf [18], 0x00)

BVGE (buf[19]@buf[18]@buf[17]@buf[16], 0x00800000)

#### Conversion to SAT

- Each arithmetic operation on bitvectors can be encoded as a circuit / formula
  - E.g., addition translated as a ripple-carry adder
- The main difficulty is removing arrays
- This is done starting from the array axioms

## Eliminating Arrays

- Transformation 1: eliminate writes
  - read(write(A, i, v), j)  $\Leftrightarrow$  ite(i=j, v, read(A, j))
  - a write by itself (not inside a read) is meaningless and can be discarded
- Transformation 2: eliminate reads
  - a) replace each syntactically-unique read by a fresh variable
  - b) add array axioms: for each pair of indexes, if the indexes are equal, so are the corresponding introduced variables

## Eliminating Reads

$$(a[i_1] = e_1) \land (a[i_2] = e_2) \land (a[i_3] = e_3) \land (i_1 + i_2 + i_3 = 6)$$
$$(v_1 = e_1) \land (v_2 = e_2) \land (v_3 = e_3) \land (i_1 + i_2 + i_3 = 6)$$
$$(i_1 = i_2 \implies v_1 = v_2) \land (i_1 = i_3 \implies v_1 = v_3) \land (i_2 = i_3 \implies v_2 = v_3)$$

STP's read elimination is expensive:

Expands each formula by  $n \cdot (n-1)/2$  terms, where n is the number of syntactically distinct indexes

STP's conversion of array terms to SAT is expensive  $(a[i_1] = e_1) \land (a[i_2] = e_2) \land (a[i_3] = e_3) \land (i_1+i_2+i_3=6)$   $(v_1 = e_1) \land (v_2 = e_2) \land (v_3 = e_3) \land (i_1+i_2+i_3=6)$  $(i_1 = i_2 \rightarrow v_1 = v_2) \land (i_1 = i_3 \rightarrow v_1 = v_3) \land (i_2 = i_3 \rightarrow v_2 = v_3)$ 



STP's conversion of array terms to SAT is expensive  $(a[i_1] = e_1) \wedge (a[i_2] = e_2) \wedge (a[i_3] = e_3) \wedge (i_1 + i_2 + i_3 = 6)$  $(v_1 = e_1) \wedge (v_2 = e_2) \wedge (v_3 = e_3) \wedge (i_1 + i_2 + i_3 = 6)$  $\frac{(i_1 = i_2 \rightarrow v_1 = v_2) \wedge (i_1 = i_3 \rightarrow v_1 = v_3) \wedge (i_2 = i_3 \rightarrow v_2 = v_3)}{(i_1 = i_3 \rightarrow v_1 = v_3) \wedge (i_2 = i_3 \rightarrow v_2 = v_3)}$  $i_{1} = 1$   $i_{2} = 2$   $i_{3} = 3$   $v_{1} = e_{1} = 1$   $v_{2} = e_{2} = 2$   $v_{2} = e_{3} = 3$  $(a[1] = 1) \land (a[2] = 2) \land$  $(a[3] = 3) \land (1+2+3 = 6)$ 

STP's conversion of array terms to SAT is expensive  $(a[i_1] = e_1) \wedge (a[i_2] = e_2) \wedge (a[i_3] = e_3) \wedge (i_1 + i_2 + i_3 = 6)$  $(v_1 = e_1) \wedge (v_2 = e_2) \wedge (v_3 = e_3) \wedge (i_1 + i_2 + i_3 = 6)$  $\frac{(i_1 = i_2 \rightarrow v_1 = v_2) \wedge (i_1 = i_3 \rightarrow v_1 = v_3) \wedge (i_2 = i_3 \rightarrow v_2 = v_3)}{(i_1 = i_3 \rightarrow v_1 = v_3) \wedge (i_2 = i_3 \rightarrow v_2 = v_3)}$  $i_{1} = 2$   $i_{2} = 2$   $i_{3} = 2$   $v_{1} = e_{1} = 1$   $v_{2} = e_{2} = 2$   $v_{3} = e_{3} = 3$ (a[2] = 1) ∧ (a[2] = 2) ∧ (a[2] = 3) ∧ (2+2+2 = 6)

STP's conversion of array terms to SAT is expensive  $(a[i_1] = e_1) \wedge (a[i_2] = e_2) \wedge (a[i_3] = e_3) \wedge (i_1 + i_2 + i_3 = 6)$  $(v_1 = e_1) \wedge (v_2 = e_2) \wedge (v_3 = e_3) \wedge (i_1 + i_2 + i_3 = 6)$  $(i_1 = i_2 \rightarrow v_1 = v_2) \wedge (i_1 = i_3 \rightarrow v_1 = v_3) \wedge (i_2 = i_3 \rightarrow v_2 = v_3)$  $i_{1} = 2$   $i_{2} = 2$   $i_{3} = 2$   $v_{1} = e_{1} = 1$   $v_{2} = e_{2} = 2$   $v_{2} = e_{3} = 3$  $(a[2] = 1) \land (a[2] = 2) \land$  $(a[2] = 3) \land (2+2+2 = 6)$ 

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- When unsuccessful, which axioms to add?
- Different heuristics possible
- STP finds an array index that violates an axiom and adds all axioms involving that index

#### Evaluation

| Solver                       | Total time (min) | Timeouts |
|------------------------------|------------------|----------|
| STP (baseline)               | 56               | 36       |
| STP (array-based refinement) | 10               | 1        |



8495 test cases from our

symbolic execution benchmarks

• Timeout set at 60s (which are added as penalty), underestimates performance differences

#### **SMT Solvers**

- SMT solvers support rich theories in classical firstorder logic with equality
  - E.g., theory of Presburger arithmetic, theory of bitvectors and arrays, theory of rationals, etc.
- Approaches for SMT solving include
  - Eager translation to SAT
  - DPLL[T]
  - Nelson-Oppen framework for combining different theories